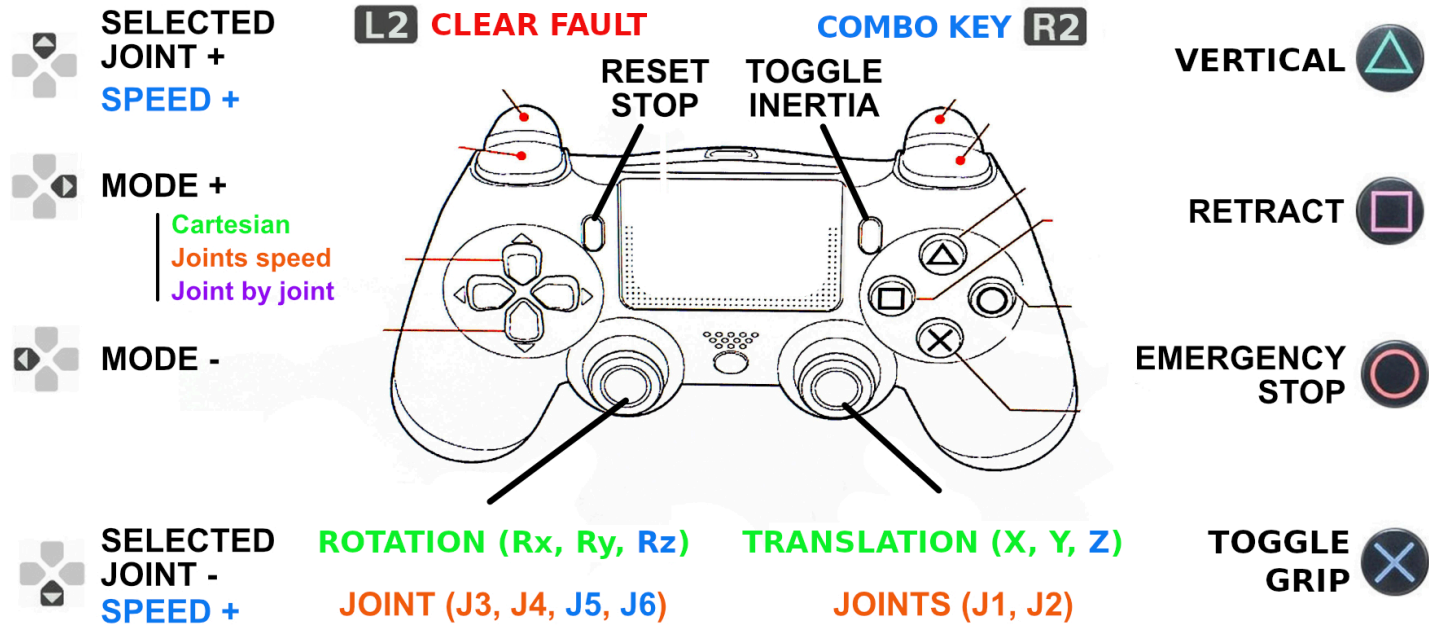


Part 1: Single Arm motion

Within 'aimrantw/icra24_tutorial:init_robots_tutorial' docker.

For teleoperation:

- source blender_ws/devel/setup.bash
- roslaunch blender-animator gen3_lite_<real/sim>_arm_teleop.launch



For Blender editing:

- rosbag record /mobile_manip/joint_states -O creation.bag
- rosruntime blender-animator bag2blender.py creation.bag
- roslaunch blender-animator gen3_lite_blender_animation.launch